AMENDMENTS TO THE SPECIFICATION

Please amend the specification as follows:

Page 2, the second full paragraph is amended as follows:

Therefore, when an value input by a user is improper, a vehicle can deviate from the prescribed route. In this case, information indicating in what way a vehicle deviated from a route is by no means reflected upon the next route guidance in order to automatically correct a route guidance. For this reason, when a user took-takes the same route again, the user is in danger of repeatedly committing a similar deviation from a route to the past.

Page 5, the last full paragraph is amended as follows:

The route deviant position determining means 6 is for determining whether or not a vehicle deviated from a route along which the vehicle is being guided by relaying relying upon the position detecting means 1, the map information acquiring means 2, and the route searching means 4. When the vehicle deviated from the route, the route deviant position determining means 6 detects route deviation information containing a route deviated date and hour, a route deviated position, and a route deviated situation composed of positional relationship between the route deviated position and a route guidance information output point.

Page 10, the last full paragraph is amended as follows:

This enables a route search, in which information on the past route deviation is feed backedutilized, when a vehicle travels on the same route even-the next time.

Page 12, the fourth full paragraph is amended as follows:

The update allows the information stored in the route deviant position storing means 7 to be always keeping in the latestkept in a current state according to familiarity of a driver.

Page 14, the second full paragraph is amended as follows:

If there exists some deviant positions therein (step ST24-Yes), then the device adjusts in step ST25 the cost such that the acquired map information is not liable-likely to be adopted as a search route. Otherwise (step ST24-No), the device perform-performs a route search operation in step ST26. When the cost of the map information has have been adjusted, a route search operation is executed by using the map information. In this operation, in cases getting around of a route is determined that avoids the past deviated position is if possible, the position is to be done like that. This allows reduces the likelihood of a vehicle not to be liable to deviated eviating from a guidance route.

Page 14, the third full paragraph is amended as follows:

The "cost adjustment" means that a pertinent section of the map data (link data) is modified such that the map information is not <u>liable-likely</u> to be adopted as a guidance route. For example, a distance in the map data is multiplied by a coefficient so as to make the distance longer than its actual length, and not to be liable such that the distance is not likely to be adopted the map data as a route search.

The last paragraph beginning on page 14 and ending on page 15 is amended as follows:

Moreover, when the past deviant position is not got around avoided, notification is given, which will be described in following FIG. 6.

The last paragraph beginning on page 15 and ending on page 16 is amended as follows:

As mentioned above, when the next route guidance target point is a point where a route deviation is occurred in the past, the route guidance changing means 8 changes a route guidance, and the route guidance outputting means 5 gives a notification. Thereby, a driver pays attention to a point where he/she had experienced a route deviation in the past, which conduces not to be liable to deviate reduces the likelihood of deviating from a guidance route.

The last full paragraph on page 16 is amended as follows:

Alternatively, the guidance method determining/changing means 9 may be provided for changing conditions for a route guidance given by the route guidance changing means 8, and the conditions are changed so as to select either of the above methods of a route guidance, which are different from a regular one, or to combine a plurality of methods. This permits a vehicle not to be liable to deviate to reduce the likelihood of deviating from a guidance route.

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Page 18, the fourth full paragraph is amended as follows:

The route searching means 4 can make a route search in which a route where a route deviation tends to occur, which eanables acan help reduce the likelihood of the route deviation not to be liable to occuroccurring again.

The last paragraph beginning on page 18 and ending on page 19 is amended as follows:

When the next route guidance target point is a point where a route deviation is has occurred in the past, the route guidance changing means 8 changes, e.g., output contents displayed on a route guidance display, output contents and volume of a route guidance voice, the number of times of a route guidance, and a voice speed of a route guidance, or delays or advances timing of a route guidance. Then, the route guidance changing means gives a driver a route guidance from the route guidance outputting means 5. Therefore, a driver pays attention to a point where a route deviation is occurred in the past by virtue of notification in a wide variety of ways, thereby enabling reducing the likelihood of a route deviation-not be liable to occur.

The last paragraph on page 19 is amended as follows:

The guidance method determining/changing means 9 is provided for changing conditions of a route guidance output by the route guidance changing means 8. Therefore, the conditions are changed so as to select either of the above methods of a route guidance, which are different from a regular one, or a plurality of methods by a driver's own preference, thereby expecting to allow reducing the likelihood of a route deviation not be liable to occur.

Please amend the Abstract as follows:

Deviant A deviant position determining means detector that determines whether or not a vehicle deviated from a set route, detects route deviation information such as a route deviated position when a vehicle deviated, and stores it as past route deviation information in a route deviant position storing means memory. The A route searching means device searches a route to the a destination based on information obtained by a position detecting means detector and a map information acquiring means device, and further searches past route deviation information obtained from the route deviant position storing means memory. The A route guidance changing means device determines whichever route guidance method is the best based on information obtained by the route searching means device and from the route deviant position storing means memory, and instructs a route guidance outputting means device to output the best route guidance method.